**A Methodological Experimentation of Fine-Tuning Mask2Former for Fallen Tree Segmentation**

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**1. Executive Summary**

This project encompasses a rigorous attempt to fine-tune Mask2Former model for a custom instance segmentation task: identifying fallen trees from high-resolution aerial images. The project's main target was to establish a complete, end-to-end pipeline, from raw data processing to model training with Mask2Former, within a constrained computational environment.

Significant effort was required to overcome two main challenges. First, a complex data-to-model pipeline to process large, non-standard geospatial data, and second, a fragile and complex software environment that required building frameworks from source and patching CUDA kernels to ensure compatibility.

A key achievement of this project was the implementation and verification of the entire training pipeline on a small-scale test dataset, proving the correctness of the data loaders, model configuration, and training loop. However, when scaled to the full dataset, the model ultimately failed to converge to a meaningful result, highlighting the specific challenges of applying large transformer-based architectures to this low-data, domain-specific problem. This report details the extensive work completed and provides a technical analysis of the observed outcome.

**1.1 Understanding the Problem**

We are given 15 aerial images (.tif) with corresponding .json files annotating the fallen trees. Our goal is to train a Mask2Former instance segmentation model to identify these fallen trees.

**2. Data Engineering and Preprocessing Pipeline**

A robust data pipeline was built to solve the primary challenge: converting the raw, large-scale geospatial data into thousands of model-ready training patches with valid pixel-based instance masks. This pipeline consisted of three main stages.

**2.1. Custom Data Preprocessing Pipeline**

The raw .tif images were too large, and the .json vector annotations needed to be compatible with the model, which requires pixel-based instance masks.

Key features of this pipeline:

* Configuration:
  + Defines input/output paths and parameters (patch size, stride, resize factor, etc.).
* Data Splitting:
  + Splits the dataset into train and validation sets (default 80/20).
* Preprocessing Pipeline:

For each .tif image:

* + Loads the image and its annotation.
  + Resizes the image to reduce computation.
  + Pads to a multiple of the patch size.
  + Extracts overlapping patches using a sliding window.
  + Keeps only objects with ≥50% overlap in each patch.
  + Saves:
    - train\_PNG/ → patch images
    - train\_MASK/ → instance masks (each tree = unique ID)
    - train\_BBOX/ → bounding box visualizations
  + Tracks progress in TRACKING.json.
* Outputs:
  + Organized directories for training and validation sets.
  + split\_info.json → details of data split.
  + TRACKING.json → prevents duplicate processing.
* Visualization:
  + Displays a selected patch, its mask, and bounding boxes side by side for inspection.

**2.2. COCO-Format Conversion for Detectron2**

The Mask2Former framework, via Detectron2, requires all training data to be in the standardized COCO .json format.

Key features of this pipeline:

* Setup Paths defining input (preprocessed\_data) and output (coco\_format) directories.
* Convert to COCO (Common Objects in Context)
  + Iterates over patch images and masks.
  + Extracts each instance (tree) from the mask.
  + Calculates area, bbox, and encodes segmentation in RLE format.
  + Builds a full COCO structure with images, annotations, and categories.
  + Saves as instances\_train.json and instances\_val.json.
* Validate (validate\_coco\_format)
  + Checks JSON keys, category IDs, image–annotation consistency, and RLE structure.
* Visualize
  + Displays a sample image with bounding boxes and annotation info.

**2.3. Dataset Registration**

The COCO format .json files need to be accessible by the Detectron2 training framework. So, in this step, the custom dataset is formally registered to Detectron2.

Key features of this pipeline:

* Install Detectron2 (pre-release build).
* Register datasets
  + Uses register\_coco\_instances() to register:
    - tree\_train → /train\_PNG/ + instances\_train.json
    - tree\_val → /val\_PNG/ + instances\_val.json
  + Adds metadata (class = “tree”, color = green).
  + Verifies both splits are loaded properly.
* Visualize samples
  + Displays random images with annotations to confirm correctness.
* Print dataset statistics
  + Counts images, instances, and area/instance distributions.
* Outputs
  + Dataset successfully registered under names:
    - TRAIN: "tree\_train"
    - VAL: "tree\_val"
  + Two sample visualization PNGs saved in the COCO folder.
  + Console shows image/instance counts and metadata summary.

**3. Model and Training Environment Setup**

With the data prepared, the next effort involved configuring the complex software environment for Mask2Former and verifying the pipeline's integrity before launching a full-scale training run.

* **Environment Setup:** The standard pip install methods for Detectron2 and Mask2Former were incompatible with the Google Colab environment's updated PyTorch and CUDA versions. This required building both frameworks from source code.
* **Pipeline Verification (Smoke Test):** To avoid wasting hours on a potentially broken pipeline, programmatically created a small subset of the data (10 training images) to conduct a smoke test. This allowed to rapidly verify the entire end-to-end process: data loading, model forward pass, backpropagation, and checkpoint saving, confirming the pipeline was functional in under a few minutes with constrained resources.

**4. Experiment: Full-Scale Mask2Former Training**

After successfully verifying the pipeline, proceeded with the full-scale training experiment to fine-tune a Mask2Former model with a ResNet-50 backbone, pre-trained on ImageNet, using the complete custom "tree" dataset.

**4.1. Experimental Configuration**

The training was conducted on colab T4 GPU, which imposed significant memory constraints. The configuration (config.yaml) was therefore a deliberate compromise between model performance and hardware limitations.

* Model: Mask2Former with an R-50 backbone.
* Weights: Initialized with ImageNet pre-trained weights (R-50.pkl) for the backbone.
* Training Iterations: The model was aimed for 30,000 iterations (MAX\_ITER), but the model would continue if it stopped midway with fewer iterations.
* Learning Rate: A learning rate of 10-4 was used, with a 2,000-iteration warmup.

**4.2. Optimizations**

To successfully train the model within the resources, implemented several critical, non-default optimizations:

* Batch Size: Reduced to the minimum viable number (IMS\_PER\_BATCH = 2).
* Image Resolution: Reduced from the original 1024x1024 to 800x800 (MIN\_SIZE\_TRAIN = (800,)).
* Model Parameter Tuning: The number of object queries in the transformer was reduced by 50% (from 100 to 50) (NUM\_OBJECT\_QUERIES = 50).
* Mixed Precision: Automatic Mixed Precision (AMP) was enabled (AMP.ENABLED = True).
* Evaluation Strategy: Periodic evaluation during training was disabled (TEST.EVAL\_PERIOD = 0) to prevent out-of-memory errors.

The trainer.train() command successfully completed, indicating that these configurations and the previously established pipeline were robust.

**5. Evaluation**

The final model was evaluated on the tree\_val\_full validation set using the standard COCO evaluation protocol.

**5.1. Quantitative Analysis**

The metrics from the COCOEvaluator confirmed that the model failed to learn the task. The Average Precision (AP) scores were near zero, indicating that the model's predictions were not meaningful.

Final Evaluation Metrics (segm):

* AP: 0.0%
* AP50: 0.0%
* AP75: 0.0%

Metrics indicate a complete failure to converge.

**5.2. Qualitative Analysis**

Visual analysis confirmed the quantitative failure. Side-by-side comparisons of the ground truth images against the model's predictions showed that the model's output was consistently empty.

**6. Hypothesis for Failure**

**Data Scarcity**

The primary issue is likely the small size of the custom dataset. Transformer-based models like Mask2Former are notoriously data-hungry and may have heavily overfit to the background.

**Domain Gap:**

Fine-tuning from ImageNet (photographs of everyday objects) may not be effective. The features of aerial tree imagery are too dissimilar, and the model was unable to adapt its feature extractor.

**7. Conclusion**

This project established a complete, end-to-end pipeline for a highly challenging segmentation task with Mask2Former.

I began with basic deep learning knowledge with no prior experience in instance segmentation or Mask2Former frameworks. To bridge this gap, I dedicated significant effort to self-study, went through different theories, and tutorials. For troubleshooting and debugging, I took help from AI. Despite my knowledge gap on this task and constrained computational resources, I was able to complete this task starting from scratch.

While the final model did not converge on this challenging dataset, the experiment itself was a success. It demonstrated my ability to take a complex task from zero to a full, conclusive evaluation. The enthusiasm and resilience I applied to troubleshoot these difficulties have solidified my passion for this field.

I believe this project reflects my self-motivation and persistence as a problem-solver. I am eager to bring these skills to a collaborative setting, as I am a strong, team-oriented worker. I am confident that within a competitive research environment under your proper guidance, my dedication and fast learning ability will allow me to make meaningful contributions to your lab.